## S1 File

SAS code used to implement the multiple-locations-monitored decision model.

SYNTAX USED IN THE WHERE AND WHEN AT WORK STUDY TO APPLY LOCATION CLASSIFICATIONS FOR SINGLE-LOCATION-MONITORED APPROACH AND HEURISTIC MODEL FOR MULTIPLE-LOCATIONS-MONITORED APPROACH. INPUT DATA: ActiGraph Link files, 10-s epoch, exported as csv, with some reformatting --csv files for each participant stored in a single folder, files begin with the participant ID (numeric), with folder. ID and .csv being sufficient to uniquely identify files. --Variables: 1) timestamp: date time to the nearest minute obtained from the ActiLife software 2) officedesk, officewall, Entry, Kitchen, Photocopy, wall1, wall2, wall3, and wall4 are respectively the fields containing the Link proximity data for the sensor placed at the participant's office desk, office wall, kitchen, photocopy room, and the 2-4 beacons [depending on the floor] placed in the corridors. -- Row 1 after the heading contains example fake data to ensure all fields are assigned have a consistent format and field width to suit all files and allow appending. OUTPUT DATA: master&wearloc &win for the specified wear location "thigh" and the specified time windows for the majority vote used (1,3,5,7,9,11,13,19,25) with 5 being optimal in Where And When At Work, e.g., masterthigh 5 AUTHORSHIP: Elisabeth Winkler, Stewart Trost, Bronwyn Clark on behalf of the Centre of Research Excellence on Sitting Time and Chronic Disease Prevention - Mechanisms, Measurement and Interventions USAGE AND ADAPTATION: permitted with citation of the article in which this program appears \*Label the possible location values (0-4); proc format; value locs noe 1="office" 2="kitchen" 3="photocopy room" 4="corridors" 0="workplace-other"; run; %macro link10s(id); \*\*\*\*\* SECTION 1: - READING IN THE DATA, ENSURING IDENTIFIERS FOR PERSON, DATE AND TIME ARE PRESENT AND SUFFICIENTLY DETAILED - FOR EACH EPOCH, DETERMINING SIGNAL PRESENCE/ABSENCE AT EACH BEACON AND PARTICIPANT PRESENCE/ABSENCE AT EACH LOCATION BY THE ONE-LOCATION MONITORED APPROACH - FOR EACH EPOCH, DETERMINING AT HOW MANY LOCATIONS ONE OR MORE BEACON HAD REGISTERED A SIGNAL AS PRESENT SIMULTANEOUSLY \*\*\*\*; %let rest = \*; \*\*\* files began with the participant ID; PROC IMPORT OUT= WORK.p &id DATAFILE= "&dir&id&rest..csv" DBMS=CSV REPLACE; GETNAMES=YES; DATAROW=2; RUN;

```
data p &id; set p &id;
if N =1 then delete; *** deleting N = 1 -not real data; if timestamp = . then delete; **no data;
PID = &id; *Create a varaible for the participant ID;
array link officedesk officewall Entry Kitchen Photocopy wall1 wall2 wall3 wall4;
do over link; if link ~=. then link =1; if link =. then link =0; end; *reduce to sensor signal present/not;
*single-location-monitored approach: office any, walls any, kitchen, photocopy, entry;
office any =max(of officewall, officedesk); *signal present in the office [desk or wall beacons]?;
walls_any = max(of wall1, wall2, wall3, wall4); *signal present in the corridors [at any of the wall beacons]?;
keep Timestamp pid officedesk officewall wall1 wall2 wall3 wall4 Entry Kitchen Photocopy office any walls any;
run;
*calculate which which 10-second epoch applies to each record within each timestamp;
data p &id; set p &id; by pid timestamp; if first.timestamp then do; epn=1; end; epn+1; run;
data maxep; set p &id; by pid timestamp; if last.timestamp; lastepn=epn; keep pid timestamp lastepn; run;
data p_&id; merge p_&id maxep; by pid timestamp; sec = 10*(epn - lastepn + 5); drop epn lastepn; run;
proc datasets nolist; delete maxep; run; guit;
***** SECTION 2: The majvote majority voting macro that
- OBTAININS INFORMATION REQUIRED FOR HEURISTIC MODEL [A,B]:
-- for each timewindow, calculating A1) the number of times each beacon registered a signal and A2) the maximum
number of times a beacon registered a signal
--for each epoch, calculating B) the number of locations registering a signal simultaneously
- APPLYIS THE HEURISTIC MODEL TO CLASSIFY LOCATION [C] ****;
%macro majvote(win);
proc expand data = p &id out=pnew&wearloc. &win. &id ; *A1;
convert officewall = sum officewall/ method = none transformout = (cmovsum &win);
convert officedesk = sum officedesk/ method = none transformout = (cmovsum &win);
convert kitchen = sum kitchen/ method = none transformout = (cmovsum &win);
convert photocopy = sum photocopy/ method = none transformout = (cmovsum &win);
convert wall1= sum wall1/ method = none transformout = (cmovsum &win);
convert wall2= sum wall2/ method = none transformout = (cmovsum &win);
convert wall3= sum wall3/ method = none transformout = (cmovsum &win);
convert wall4= sum wall4/ method = none transformout = (cmovsum &win);
run;
data pnew&wearloc. &win. &id ;set pnew&wearloc. &win. &id ;
maxval = max(of sum officewall, sum officedesk, sum kitchen, sum photocopy, sum wall1, sum wall2, sum wall3,
sum wall4); *A2;
sum locs = office any + kitchen + photocopy + walls any; *B;
```

```
*HEURISTIC MODEL: C1) If 0 locations recorded a signal: -> location = workplace-other;
if sum locs = 0 then do; linkpos = 0; *workplace-other; end;
*HEURISTIC MODEL: C2) If 1 locations recorded a signal: -> location = location with the signal;
if sum_locs = 1 then do; if photocopy=1 then linkpos = 3; if kitchen=1 then linkpos = 2; if walls_any=1 then linkpos
= 4; if office any=1 then linkpos = 1; end;
*HEURISTIC MODEL: C3) If >1 locations registered signals simultaneously location -> location with the greatest
number of signals recorded as present during the
timewindow [majority vote], resolving "ties" for most common by prevalence ranking;
* each subsequent classification overwrites the previous: put lowest prevalence location first and highest
prevalence location last;
if sum locs >1 then do;
if sum photocopy=maxval then linkpos = 3;*photocopy room the 4th most prevalent;
if sum kitchen=maxval then linkpos = 2;*kitchen, 3rd most prevalent;
if sum_walls=maxval then linkpos = 4;*corridors, 2nd most prevalent;
if sum officewall=maxval then linkpos = 1;*office wall beacon, office = 1st most prevalent;
if sum officedesk=maxval then linkpos = 1;*office desk beacon, office = 1st most prevalent;
if maxval = 0 then linkpos = 0; *no sensor recorded;
end;
format linkpos locs_noe.;
run;
%if &run = 1 %then %do; data master&wearloc. &win; set pnew&wearloc. &win. &id; run; %end; *CREATE new master
dataset from data of first participant;
%if &run = 2 %then %do; data master&wearloc._&win; set master&wearloc._&win pnew&wearloc._&win._&id; run;
%end;*APPPEND data from additional participants to the master dataset;
proc datasets nolist; delete pnew&wearloc. &win. &id; run; quit;
%mend maivote;
%majvote(1); %majvote(3); %majvote(5); %majvote(7); %majvote(9); %majvote(11); %majvote(13); %majvote(19);
%majvote(25);*execute majvote macro for the nominated timewindows;
proc datasets nolist; delete p_&id; run; quit;
%mend link10s;
%let dir=C:\Documents\ProjectWWaW\LinkData\Thigh\; *indicate folder that contains the relevant csv files;
%let wearloc = thigh; *indicate the wear location - here, thigh;
*execute the macro for all participants, specifying run to be 1 for the first participant and 2 thereafter for
subsequent participants;
let run = 1;
%link10s(01);
%let run = 2; *subsequent participants-> append to existing master dataset;
```

%link10s(02); %link10s(03);