Appendix S2: Shogun Implementation and Algorithm

To describe the with-bias algorithm, we start from the 2-class ν -formulation as stated in Eq. (28) in [1] and repeated here

$$\begin{split} \inf_{\boldsymbol{\alpha}'} & \frac{1}{2} \boldsymbol{\alpha}'^{\top} \mathcal{K} \boldsymbol{\alpha}' \\ \text{s.t} & \boldsymbol{y}^{\top} \boldsymbol{\alpha}' = 0, \quad \boldsymbol{\alpha}'^{\top} \mathbf{1} = \nu, \quad \mathbf{0} \leq \boldsymbol{\alpha}' \leq \frac{1}{N} \mathbf{1}. \end{split}$$

We first notice that the two equality constraints can be expressed by class-wise total weight mass conditions: $\alpha'_1^{\top} \mathbf{1} = \alpha'_{-1}^{\top} \mathbf{1} = \nu/2$. Due to these equality constraints, reasonable subproblems require $y_i = y_j$; otherwise, neither α'_i nor α'_j could be changed. Consequently this constraint is implemented by the selection strategy and a proper choice of the initial solution candiate. Note that feasible initial points also require $\nu \leq C \cdot N_{min}/N$. To recover the problem in Eq. (15) in the main manuscript, we need to perform a variable transformation $\alpha' \mapsto \frac{\alpha}{\mu \cdot N}$ combined with the choice $\nu = C/(\mu \cdot N)$.

For 2-class problems, LIBSVM's working set selection strategy for ν -SVMs (cf. WSS 5 in [1]) traverses the active set twice and thus requires an effort of $\mathcal{O}(2N+2T)$, where T is the time to compute a kernel row. A straightforward generalization traverses the active set for each of the C classes leading to an effort of $\mathcal{O}(CN+CT)$ which is what we used throughout experiments. However, when ordering examples, such that $y_i \leq y_j$ for i < j and by creating C arrays to hold the maximum class-wise gradient etc. the computational complexity can be further reduced to $\mathcal{O}(C+N+CT)$.

We now describe our without-bias algorithm. We now face the problem that due to the lack of a bias there is no sum-to-one constraint on the α_i 's anymore in the dual optimization problem, Eq. (15) in the main manuscript. Therefore the line search performed by SMO cannot be solved analytically anymore. As a remedy we implemented a without-bias solver based on SVMlight, which basically can deal with any quadratic programm. The algorithm is described in Algorithm 1. We thereby employ the notation $\mathcal{K} = \kappa(\mathbf{x}_i, \mathbf{x}_j)_{i,j=1}^n$ for the block kernel matrix as defined in Eq. (7) in the main manuscript.

The algorithm has as input an accuracy parameter ϵ (in our experiments $\epsilon = 0.001$ was chosen) and an active set size Q (Q = 40 was chosen). The main FOR loop (Lines 2-3) iterates until the stopping criterion (duality gap less than ϵ) is fulfilled. Line (a) computes the set of Q active variables based on minimal gradients. Line (b) performs the actual Scatter SVM computation w.r.t. the active variables, resulting in new values of the α_i . Line (c) updates the gradient w.r.t. the the new α_i . Line (d) computes the actual objective value of the optimization problem, Eq. (15) in the main manuscript.

Algorithm 1

1. $S^0 = -\infty, g_i = 0, \alpha_i = 0, \forall i = 1, ..., n$

2. for t = 1, 2, ... and while optimality conditions are not satisfied, i.e. $|1 - \frac{S^t}{S^{t-1}}| \ge \epsilon$

- (a) Select Q variables $\alpha_{i_1}, \ldots, \alpha_{i_Q}$ based on the gradient **g** of Eq. (15) in the main manuscript, w.r.t. $\boldsymbol{\alpha}$
- (b) Store $\alpha^{old} = \alpha$ and then update α according to Eq. (15) in the main manuscript, with respect to the selected variables
- (c) Update gradient $g_i \leftarrow g_i + \sum_{q=1}^{Q} (\alpha_{i_q} \alpha_{i_q}^{old}) y_{i_q} \kappa(\mathbf{x}_{i_q}, \mathbf{x}_i), \ \forall \ i = 1, \dots, n$
- (d) Compute the SVM objective $S^t = \sum_i y_i \alpha_i \frac{1}{2} \sum_i y_i g_{m,i} \alpha_i$

3. end for

References

1. Fan RE, Chen PH, Lin CJ (2005) Working Set Selection Using the Second Order Information for Training SVM. Journal of Machine Learning Research 6: 1889–1918.